### ■3D sensor head

	3D laser sensor	Stereo sensor		
Working distance (mm)*	100	250、400		
View area (mm)*	38×29~99×74, 3types	120×90~290×230, 4types		
Laser class	slit type 2 projector, class2	—		
LED lighting	high intensity red lamp, 4pcs	high intensity red lamp, 4pcs		
Dimension (mm)	129 (W) ×110 (H) ×122 (D)	210 (W) ×110 (H) ×49 (D)		
Weight (g)	about 950	about 1,260		
*Contact us for a special type of sennsor.				

	LSC (standard)	LSC (wide)	
Working distance (mm)*	1,400 ~ 2,000	1,700 ~ 3,500	
Measurement area (mm)*	800 (W) ×800(D) ×600(H)	1,400 (W) ×1,400 (D) ×1,800 (H)	
Laser class	class 3R	class 3R	
Dimension (mm)	610 (W)×125 (H) ×125 (D)	1,100 (W) ×125 (H) ×125 (D)	
Weight (g)	about 4.8	about 6.5	

\*Contact us for a special type of sennsor.

# Vision Processing Unit K-HIPE-R-PC



## **Features**

- · PC-based type
- Fast recognition by multi-core CPU
- · Selectable memory medea, HDD or SSD · Connectable multi-cameras or multi-sensors
- · Connectable to various equipment by Ethernet, DeviceNet,
- Serial I/O, Parallel I/O • Available 0.3~5 mega-pixel GigE camera and camera link

### CAUTIONS TO BE TAKEN TO ENSURE SAFETY

- For those persons involved with the operation / service of your system, including Kawasaki Robot, they must strictly observe all safety regulations at all times. They should carefully read the Manuals and other related safety documents.
- Products described in this catalogue are general industrial robots. Therefore, if a customer wishes to use the Robot for special purposes, which might endanger operators or if the Robot has any problems, please contact us. We will be pleased to help you.
- Be careful as Photographs illustrated in this catalogue are frequently taken after removing safety fences and other safety devices stipulated in the safety regulations from the Robot operation system.



ISO certified in Akashi Works.

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\* Materials and specifications are subject to change without notice.

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# Simple<sup>®</sup> friendly

awa:

# Kawasak **Vision System**

# High performance vision system, applied to various usages flexibly and immediately

Kawasaki's Vision system is a multifunctional, high-speed, and high-precision visual sensing system that can be used on a wide range of sites immediately. The adoption of Vision systems enables no positioning of works to be required and the initial setup per work to be simplified.

# **2D** vision system

Recognition module



## **Features**

- Fast recognition and High accuracy recognition
- Pattern matching, Binarization, and Color recognition processing
- Recognition of various objects (shapes and colors)
- Inspection, Discrimination of both sides
- Easy operation

Distribution module



## Features

 Work position is distributed to the multiple robot (max. 8) based on the result of the vision.



Model Registration Measurement Result

### Canfiguration example





**3D** vision system



## **Features**

- Kawasaki's original 3D sensor are selectable as to applied content and required accuracy.
- Insusceptible system to change of lighting environment and object's surface condition
- View area is selectable according to usages. Except 2-laser slit type, 1-laser slit type is selectable. (3D laser sensor)
- Working distance and view area are selectable according to usages. (Stereo sensor)
- Detectable by only stand-alone camera through wide area (LSC)
- On-line interference check function (bin-picking)

P1 9 P3

3D laser sensor

OF

P2

Body inspection

3D laser sensor

Container measurement

camera

# Application Bumper picking system Stereo sensor stereo sensor Sealing system Multi cameras







Example

Example

3D laser sensor

]	<b>3D</b> sensor lineup [Kawasaki Original Equipments]				
	Name	3D laser sensor	Stereo sensor	Laser slit scan camera (LSC)	
	Externals	Narrow view	Middle view	Wide view	
	Feature	Hole center, space difference, and gap measurement (Gray image)	3D-mesurement of registration pattern (Gray image)	High density 3D-measurement of work area (Distance image)	
	Usage	Measurement• inspection, Position correction	Parts picking, Position correction	Bin-picking, Environment recognition (interference avoidance)	